

Intergenerational Insurance

Alessia Russo (Padua and CEPR)

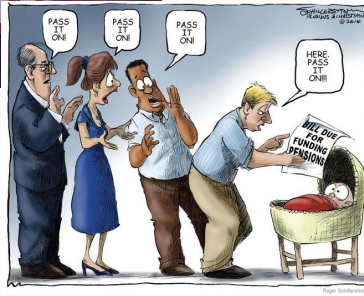
Francesco Lancia (Venice and CEPR)

Tim Worrall (Edinburgh)

Motivation



Motivation



2 minute read · April 3, 2023 1:27 PM GMT+2 · Last Updated 16 days ago

Pope says pension systems must not weigh on future generations

Reuters

Motivation

- Fiscal reforms may be difficult to implement
 - ◇ **Limited enforcement** due to political constraints
- When fiscal reforms involve different generations, a distributional **conflict** may arise
 - ◇ Conflict resolution may imply a higher fiscal burden on future generations
 - ◇ Welfare losses arise due to partial intergenerational insurance

Research Questions

- I. How should **optimal intergenerational insurance** be structured under **limited enforcement** frictions?
- II. What are the implications in terms of **risk-spreading** across generations?

What We Do

- We characterize **optimal intergenerational insurance** under **limited enforcement** when agents belong to finitely-lived **OLG**

... while the past literature has characterized:

- i. Optimal intergenerational risk sharing under **full enforcement** (e.g., Aiyagari and Peled, 1991)
- ii. Intergenerational risk sharing as a voting equilibrium, which is **not** necessarily optimal (e.g., Cooley and Soares, 1999)
- iii. Optimal risk sharing under limited enforcement when agents are **infinitely lived** (e.g., Thomas and Worrall, 1988)

Mechanism in a Nutshell

A trade-off **Incentives** versus **Efficiency**:

✓ **Incentives**: Risk is partially spread onto future generations to provide incentives to the current generation to not walk away

⇒ Consumption depends on past shocks

✓ **Efficiency**: Period *resetting* in the provision of incentives to offset the welfare losses of shocks propagation

⇒ Consumption periodically resets to welfare maximising levels

Policy Implications

- Which policy institution may support the optimal allocation?
- A combination of **taxes**, **transfers** and **state-contingent bonds** can replicate the optimal allocation
- Limited enforcement implies a **non-linear fiscal reaction function** to public debt
 - ⇒ A form of **fiscal fatigue** (Gosh et al 2013)
- Public **debt** as a **safe asset** (good hedge)
 - ⇒ High sustainable debt even if expected primary surpluses are low (Brunnermeier et al 2022, Jiang et al 2022)

Presentation Outline

- i. Model
- ii. Full enforcement
- iii. Limited enforcement
- iv. Implications for debt sustainability

Model

- Discrete time $t = 0, 1, 2, \dots, \infty$
- Two-period living agents: Young and Old
- Total endowment $e_t = e_t^y + e_t^o$ of perishable consumption good
- Aggregate (**growth**) risk $\gamma_t = \frac{e_t}{e_{t-1}}$
- Idiosyncratic (**distributional**) risk $s_t = \frac{e_t^y}{e_t} \in \{s(1), s(2)\}$ with $s(1) < s(2)$
- $\rho_t := (s_t, \gamma_t)$ with probability ω and $\rho^t := (\rho_1, \rho_2, \dots, \rho_t) \in \mathcal{P}^t$

- Young consumption $C(\rho^t)$ and old consumption $e_t - C(\rho^t)$
- Logarithmic per-period utility function $u(\cdot) = \log(\cdot)$
- Given homogenous utility we can consider the de-trended economy and characterize

$$\{c\} = \{c(\rho^t) = \frac{C(\rho^t)}{e_t} : t \geq 0, \rho^t \in \mathcal{P}^t\}$$

Planner Problem

- The planner chooses $\{c\}$ to maximize the **sum of expected discounted utility of all generations**

$$V(\{c\}; \rho^t) = \underbrace{\frac{\beta}{\delta} (\log(1 - c(\rho^t)))}_{\text{Current Old}} + \underbrace{\mathbb{E}_t \left[\sum_{j=t}^{\infty} \delta^{t-j} U(\{c\}; \rho^j) \right]}_{\text{Current Young and Fut. Gen.}}$$

where

$$U(\{c\}; \rho^t) = \log(c(\rho^t)) + \beta \sum_{\rho_{t+1}} \omega(\cdot, \rho_{t+1}) \log(1 - c(\cdot, \rho_{t+1}))$$

- **Participation constraints of the old:**

$$c(\rho^t) \leq s_t \quad (1)$$

- **Participation constraints of the young:**

$$U(\{c\}; \rho^t) \geq \log(s_t) + \beta \sum_{\rho_{t+1}} \omega(\cdot, \rho_{t+1}) (\log(1 - s_{t+1})) \quad (2)$$

Optimal Sustainable Intergenerational Insurance

- An Intergenerational Insurance rule is **sustainable** if the history-dependent consumption plan

$$\{c(\rho^t)\}_{t=0}^{\infty} \in \Lambda := \{\{c(\rho^t)\}_{t=0}^{\infty} \mid (1) \text{ and } (2)\}$$

- A Sustainable Intergenerational Insurance rule is **optimal** if it maximizes $V(\{c\}; \rho^t)$ subject to the constraint that the initial old receive a utility of at least ω_0 :

$$\log(1 - c(\rho_0)) \geq \omega_0$$

Assumptions

Assumption (1)

The idiosyncratic and aggregate shocks are iid: $\omega(\rho) = \pi(s)\zeta(\gamma)$

⇒ Any sustainable intergenerational insurance rule $\{c\}$ depends **only** on the history of **idiosyncratic shocks**

Assumption (2)

$$\beta \sum_r \pi(r) \frac{s}{1-r} > 1$$

⇒ There **exists** a non-trivial sustainable intergenerational insurance that improves upon autarky

Recursive Formulation

- Let ω_r be the **state-contingent promise** to current young when next-period state is r and the promise to current old is ω
- The planner's optimization problem is:

$$V(s, \omega) = \max_{\{c, (\omega_r)_{r \in \mathcal{I}}\}} \frac{\beta}{\delta} \log(1 - c) + \log(c) + \delta \sum_r \pi(r) V(r, \omega_r)$$

subject to

$$BC : \omega_{\min}(r) \leq \omega_r \leq \omega_{\max}(r)$$

$$PC_o : c \leq s$$

$$PC_y : \log(c) + \beta \sum_r \pi(r) \omega_r \geq \log(s) + \beta \sum_r \pi(r) \log(1 - r)$$

$$PK : \log(1 - c) \geq \omega$$

For This Presentation

Simplifying assumptions:

- $\beta = \delta$
- BC and PC_0 are not binding

Notation:

- μ is the multiplier associated with PC_y
- λ is the multiplier associated with PK
- $c = \mathbf{c}(x)$ and $\omega_r = \mathbf{w}_r(x)$ with $x := (s, \omega)$ are the optimal consumption and state-contingent promised utility

Full Enforcement

- The Planner value $V(s, \omega)$ is subject to PK, but not PCy
- The first-order conditions are:

$$\frac{1 - \mathbf{c}(x)}{\mathbf{c}(x)} = 1 + \lambda(x) \quad \text{and} \quad V_{\omega}(r, \mathbf{w}_r(x)) = 0$$

The envelope condition is:

$$V_{\omega}(x) = -\lambda(x)$$

Full Enforcement

- The Planner value $V(s, \omega)$ is subject to PK, but not PCy
- The first-order conditions are:

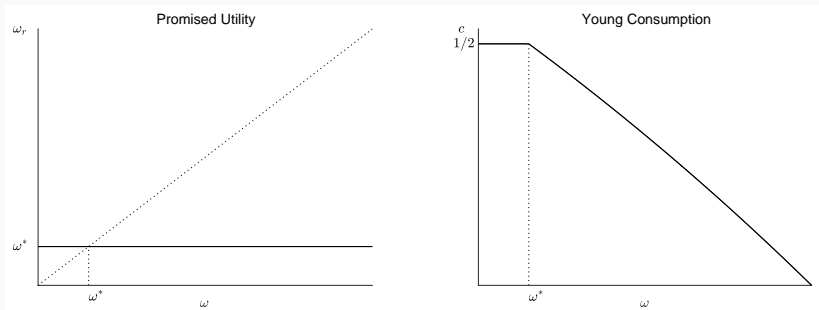
$$\frac{1 - \mathbf{c}(x)}{\mathbf{c}(x)} = 1 + \lambda(x) \quad \text{and} \quad V_{\omega}(r, \mathbf{w}_r(x)) = 0$$

The envelope condition is:

$$V_{\omega}(x) = -\lambda(x)$$

- There is $\omega^* = \log\left(\frac{1}{2}\right) = \sup\{\omega \mid V_{\omega}(x) = 0\}$
- \Rightarrow If $\omega_0 \leq \omega^*$ then $\lambda = 0$ and $c_0 = c^* := \mathbf{c}(s_0, \omega^*) = \frac{1}{2}$
- \Rightarrow If $\omega_0 > \omega^*$ then $\lambda > 0$ and $c_0 = \mathbf{c}(s_0, \omega_0) = 1 - \exp(\omega_0)$
- $\Rightarrow \mathbf{w}_r(s_0, \omega_0) = \omega^*$ for any ω_0, s_0 , and r

Full Enforcement



Proposition

Under **full enforcement**, the optimal allocation is **stationary** and the long-run distribution of ω is **degenerate** with mass at ω^*

Limited Enforcement

- The Planner value $V(s, \omega)$ is subject to both PK and PCy
- The first-order conditions are:

$$\frac{1 - \mathbf{c}(x)}{\mathbf{c}(x)} = \frac{1 + \lambda(x)}{1 + \mu(x)} \quad \text{and} \quad V_{\omega}(r, \mathbf{w}_r(x)) = -\mu(x)$$

The envelope condition is:

$$V_{\omega}(x) = -\lambda(x)$$

⇒ Updating rule:

$$V_{\omega}(r, \mathbf{w}_r(x)) = -\lambda(r, \mathbf{w}_r(x)) = -\mu(x)$$

Limited Enforcement

- The Planner value $V(s, \omega)$ is subject to both **PK** and **PCy**
- The first-order conditions are:

$$\frac{1 - \mathbf{c}(x)}{\mathbf{c}(x)} = \frac{1 + \lambda(x)}{1 + \mu(x)} \quad \text{and} \quad V_{\omega}(r, \mathbf{w}_r(x)) = -\mu(x)$$

The envelope condition is:

$$V_{\omega}(x) = -\lambda(x)$$

⇒ Updating rule:

$$V_{\omega}(r, \mathbf{w}_r(x)) = -\lambda(r, \mathbf{w}_r(x)) = -\mu(x)$$

- There is $\omega^0(s) = \sup\{\omega \mid V_{\omega}(s, \omega) = 0\} \leq \omega^* \quad \forall s$

⇒ If $\omega_0 \leq \omega^0(s_0)$ then $\lambda = 0$ and $c_0 = \mathbf{c}(s_0, \omega^0(s_0)) \geq \frac{1}{2}$

⇒ If $\omega_0 > \omega^0(s_0)$ then $\lambda > 0$ and $c_0 = \mathbf{c}(s_0, \omega_0) = 1 - \exp(\omega_0)$ 17

Dynamics of Promised Utility

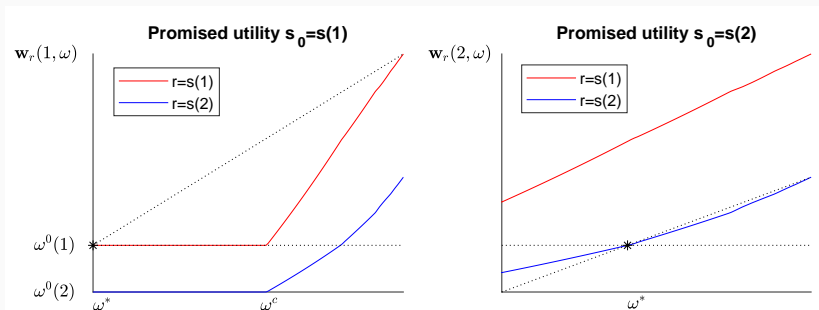
- The Planner would like to promise $\omega^0(s)$ to the current young
- But if PC_y is binding, the current young will refuse it
- In this case, the Planner must promise more to relax PC_y of the current young
- A higher promised utility means that more consumption must be delivered to next-period old, which tightens PC_y of future young

Proposition

Assume that c^* violates PC_y in at least one s and $s(\mathbf{1}) \leq c^*$, the optimal policy $\mathbf{w}_r(s, \omega)$ is

- increasing in ω
- increasing in s
- decreasing in r
- there is a critical $\omega^c > \omega^0(\mathbf{1})$ such that $\mathbf{w}_r(\mathbf{1}, \omega) = \omega^0(r)$ if $\omega \leq \omega^c$ (**resetting**)
- there is a unique fixed point $\omega^f(s) = \mathbf{w}_s(s, \omega^f(s)) = \omega^* \forall s$

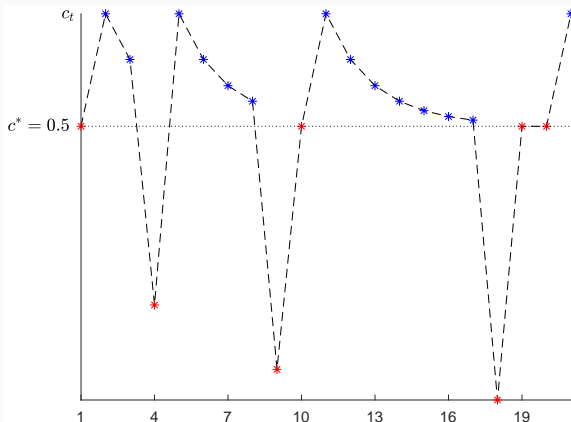
Dynamics of Promised Utility



Proposition

*Under **limited enforcement**, the optimal allocation is **history dependent** and the long-run distribution of ω is non degenerate in an ergodic set with countable infinite states*

Dynamics of Consumption



Consumption of adjacent generations is serially **correlated** and does **not** follow a random walk

Stochastic Discount Factor

- In an equilibrium model, the SDF is

$$M_{t,t+1} = \beta \frac{u'(e_{t+1} - C(\rho^{t+1}))}{u'(C(\rho^t))}$$

- In the sustainable optimal allocation, the SDF is

$$M_{t,t+1} = \delta \cdot \underbrace{\frac{\mathbf{c}(x_t)/(1 + \mu(x_t))}{\mathbf{c}(x_{t+1})/(1 + \mu(x_{t+1}))}}_{m_{t,t+1}} \cdot \frac{e_t}{e_{t+1}}$$

Stochastic Discount Factor

- In an equilibrium model, the SDF is

$$M_{t,t+1} = \beta \frac{u'(e_{t+1} - C(\rho^{t+1}))}{u'(C(\rho^t))}$$

- In the sustainable optimal allocation, the SDF is

$$M_{t,t+1} = \delta \cdot \underbrace{\frac{c(x_t)/(1 + \mu(x_t))}{c(x_{t+1})/(1 + \mu(x_{t+1}))}}_{m_{t,t+1}} \cdot \frac{e_t}{e_{t+1}}$$

Proposition

- Under **full enforcement**, the SDF is $M_{t,t+1}^* = \delta \frac{e_t}{e_{t+1}}$.
- Under **limited enforcement**, the SDF is decreasing in γ_{t+1} , increasing in s_{t+1} and decreasing (non-linearly) in ω_t

Sustainable Public Debt

- The Planner uses one-period **state-contingent bond** $B_{r,t+1}$ in zero net supply and **taxes** \mathcal{T}_t to repay **outstanding debt** D_t

$$D_t = \mathcal{T}_t + \sum_r q_{r,t+1} B_{r,t+1}$$

where **state prices** are

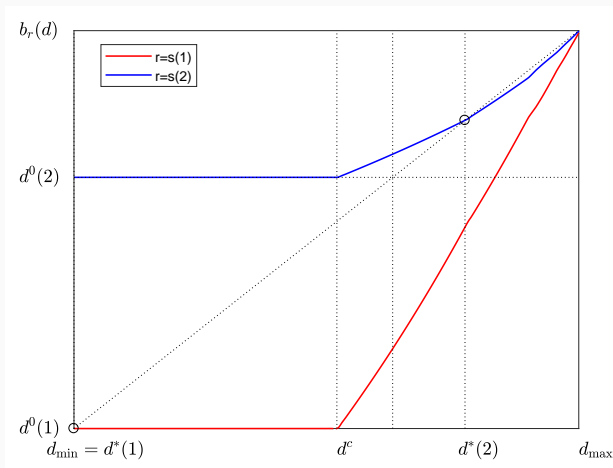
$$q_{r,t+1} := \pi(r) M_{t,t+1} = \pi(r) \beta \frac{u'(e_{t+1}^o + B_{r,t+1})}{u'(e_t^y - \mathcal{T}_t - \sum_r q_{r,t+1} B_{r,t+1})}$$

- Let $d_t := \frac{D_t}{e_t s_t}$, $\tau_t := \frac{\mathcal{T}_t}{e_t s_t}$ and $b_{r,t+1} := \frac{B_{r,t+1}}{e_{t+1} s_{t+1}}$

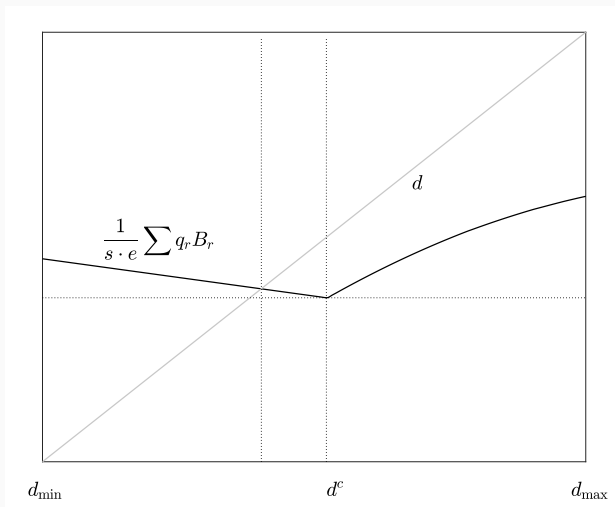
Dynamics of Debt

Dynamics of promises \iff Dynamics of debt

$$\omega_t = \log(1 - c_t) = \log(1 - s_t(1 - d_t)) \rightarrow d_t = \mathbf{d}(s_t, \omega_t)$$

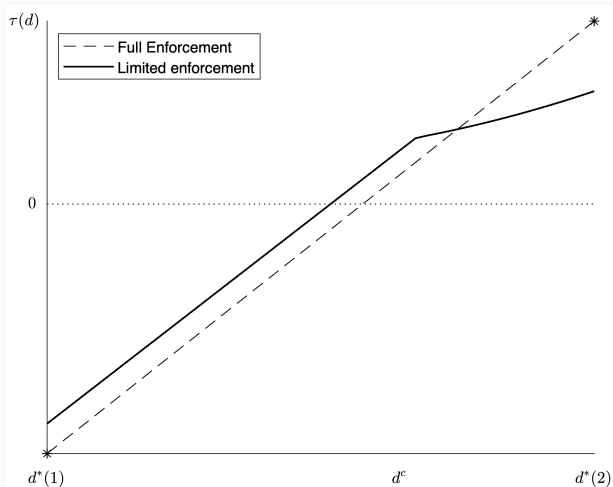


Bond Revenue



Below d^c bond revenue decreases since bond prices decrease and bond issuance is constant. Above d^c bond revenue can increase

Fiscal Reaction Function



The fiscal reaction function is non-linear in the outstanding debt:
a form of fiscal-fatigue

Debt Valuation

- Under transversality condition, the budget constraint is

$$D_t = \mathcal{T}_t + \overbrace{\sum_{j=1}^{\infty} \mathbb{E}_t[M_{t,t+j}\mathcal{T}_{t+j}]}^{\text{NPV Primary Surpluses}}$$

where

$$\mathbb{E}_t[M_{t,t+j}\mathcal{T}_{t+j}] = \mathbb{E}_t[M_{t,t+j}] \cdot \mathbb{E}_t[\mathcal{T}_{t+j}] + \text{COV}_t[M_{t,t+j}, \mathcal{T}_{t+j}]$$

- If $\text{COV}_t[M_{t,t+j}, \mathcal{T}_{t+j}] > (<=)0$, then the sustainable debt is larger(lower) than the sum of future surpluses discounted at the risk free rate $\mathbb{E}_t[M_{t,t+j}]$

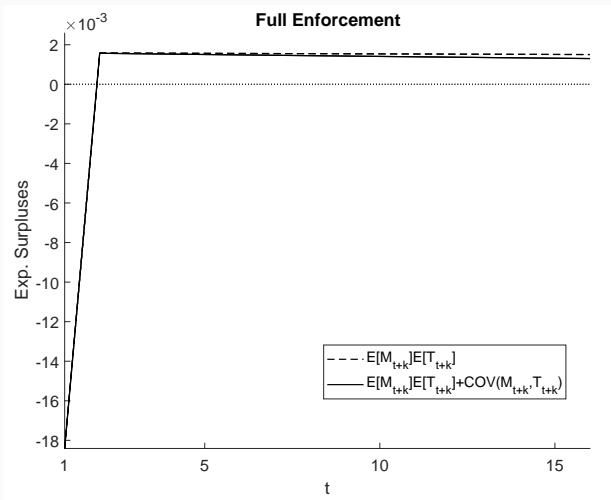
Debt Valuation

- Surplus \mathcal{T}_{t+k} increases with both γ_{t+k} (pro-cyclical) and s_{t+k}
- The SDF $M_{t,t+k}$ decreases with γ_{t+k} (counter-cyclical) and increases with s_{t+k}

⇒ The $COV_t[M_{t,t+k}\mathcal{T}_{t+k}]$ can be decomposed in two terms

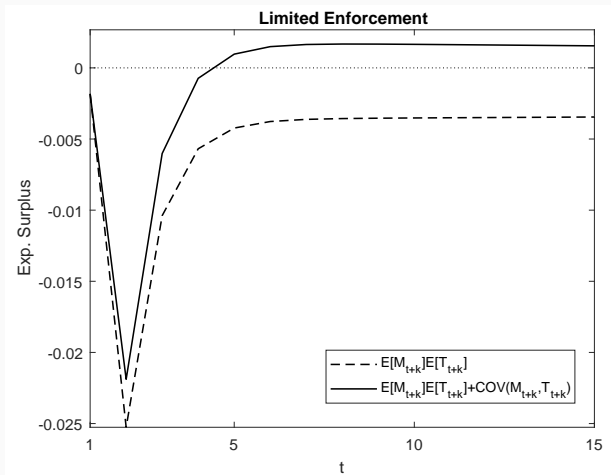
$$\underbrace{\mathbb{E}_t[m_{t,t+k}]\mathbb{E}[s_{t+k}\tau_{t+k}]}_{\geq < 0} \left(1 - \mathbb{E} \left(\frac{1}{\gamma} \right)^k \mathbb{E}(\gamma)^k \right) \\ + \underbrace{\mathbb{E}_t[m_{t,t+k}s_{t+k}\tau_{t+k}] - \mathbb{E}_t[m_{t,t+k}]\mathbb{E}[s_{t+k}\tau_{t+k}]}_{> 0}$$

Full Enforcement: $\frac{D_1}{e_1} = 0.10$



Under full enforcement, a positive amount of debt can be sustained only if expected future surpluses

Limited Enforcement: $\frac{D_1}{e_1} = 0.10$



Under limited enforcement, a positive amount of debt can be sustained even if expected future deficits (debt as good hedge)

Conclusions

- We developed a theory of intergenerational insurance in a stochastic OLG model under limited enforcement
- The model implies that:
 - i. Generational risk is spread across future generations because of the consecutive participation constraints
 - ii. The optimum provides the basis for the design of a sustainable public debt

Conclusions

- We developed a theory of intergenerational insurance in a stochastic OLG model under limited enforcement
- The model implies that:
 - i. Generational risk is spread across future generations because of the consecutive participation constraints
 - ii. The optimum provides the basis for the design of a sustainable public debt
- Potential directions for future research:
 - i. Richer demographic structure
 - ii. Storage technology

Appendix

Value Function Under Full Enforcement

